

ESC-GS EG ACPPM

PRELIMINARY REPORT ON

# SYSTEM NEEDS THAT REQUIRE ADVANCED CAPABILITIES FOR GRID STABILITY

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# AGENDA

## 01 Need for new capabilities to maintain stability

- / Phase jump power and amplitude jump power
- / Inertia power
- / Stability
- / Protection and operational needs in Distribution grids

## 02 Basic characteristics of grid-forming power park module

## 03 Characteristics needed according to the Operational Network Codes

System Needs that require advanced capabilities for grid stability

# NEED FOR NEW CAPABILITIES TO MAINTAIN STABILITY

- / For obtaining stability, 2 preconditions have to be fulfilled:
  - 1) An instantaneous compensation of a sudden imbalance of active and reactive power caused by a disturbance.
  - 2) The stable and well-damped voltage and frequency behaviour of the system as a result of the stable and well-damped voltage and frequency control loops of the power generation modules.
- / Precondition 1 requires grid forming capabilities to provide phase jump power and amplitude jump power.
- / Precondition 2 requires inertia power as well as the appropriate design of the control loops for FSM, LFSM and voltage control.

System Needs that require advanced capabilities for grid stability

## PHASE JUMP POWER AND AMPLITUDE JUMP POWER

The provision of phase jump power and amplitude jump power with an instantaneous response is required:

- / to ensure instantaneous active power balance in case of load or generation changes,
- / to provided instantaneous short circuit current,
- / to provide harmonic and asymmetric loads and
- / to provide sufficient voltage stability to allow for grid following inverters to operate.

System Needs that require advanced capabilities for grid stability

## INERTIA POWER

In [2] the ENTSO-E Project Inertia Team quantifies the need for additional inertia  
/ to ensure RoCoF values remain within acceptable limits.

Another effect of inertia power is crucial:

/ The creation of a system frequency which is reflecting the actual mismatch of active power in the system

/ Inertia power has to adapt the internal frequency depending on the active power exchange with the network

[2] Project Inertia Team, "ENTSO-E, FREQUENCY STABILITY IN LONG-TERM SCENARIOS AND RELEVANT REQUIREMENTS",  
[https://eepublicdownloads.azureedge.net/clean-documents/Publications/ENTSO-E%20general%20publications/211203\\_Long\\_term\\_frequency\\_stability\\_scenarios\\_for\\_publication.pdf](https://eepublicdownloads.azureedge.net/clean-documents/Publications/ENTSO-E%20general%20publications/211203_Long_term_frequency_stability_scenarios_for_publication.pdf), 2021.

# STABILITY

- / To ensure a stable power system operation, the provision of phase jump power and inertia power, together with the provision of FSM and LFSM must operate in a stable manner.
- / If a large share of power generation modules behave in a similar way, the sum of generation modules has a direct effect on the grid. There is a direct feedback loop between the generation module and the grid.
- / If a large share of power generation modules behave in a similar way, the system behaviour of such a system can be simulated and modelled in a simplified way in which one power generation module supplies only a single load
- / Therefore, a closed loop setup representing the relevant grid disturbance scenarios to be considered shall be used when testing the stability of
  - / LFSM
  - / voltage control loops and
  - / if applicable (e.g. for PPMs) the control loops for amplitude jump power, phase jump power and inertia power.

# PROTECTION AND OPERATIONAL NEEDS IN DISTRIBUTION GRIDS

- / Grid-forming generation (synchronous as well as converter based) pose challenges to DSOs
  - / Interaction with tap changers
  - / Reactive power exchange
  - / Behaviour during fault
  - / Islanding risk and possibly resulting risks to safety of persons
- / So far neither detailed preliminary study nor real scale demonstrator of a distribution system equipped with a significant share of grid-forming generators has been performed and tested.
- / This must be considered when connecting grid forming PGM to DSO grids, especially on LV and within the MV grid.

# BASIC CHARACTERISTICS OF GRID-FORMING POWER PARK MODULE

- / **Creating system voltage and contribution to fault level**
  - / A grid-forming PPM behaves like a voltage source behind an impedance. The dynamics of the internal voltage magnitude and angle is limited, and lags the grid dynamics.
  - / As a consequence, stabilizing and equalizing currents occur between the grid voltage and the internal source voltage of the grid forming PPM.
  - / Fast current limitation prevents currents above rated values .
    - / The current limitation is designed in a way to maintain synchronism.



# BASIC CHARACTERISTICS OF GRID-FORMING POWER PARK MODULE

- / **Provision of electrical inertia (Contribution to Inertia)**
- / **within the design limits**
  - / The internal voltage's frequency behaviour following an active power unbalance is proportional to this active power unbalance after a finite time
  - / A fast current and active power limitation prevents a power supply outside the design limits or an excessive charge/discharge of the inherent energy storage.
    - / The current and power limitation is designed in a way to maintain synchronism.
- / **within dedicated energy storage**
  - / Additional electrical inertia might be provided by a dedicated energy storage

# CHARACTERISTICS NEEDED ACCORDING TO THE OPERATIONAL NETWORK CODES

- / The characteristics needed in abnormal state of the grid (see SOGL Art. 18) have to be analysed in a system with a majority of PPMs
- / The expert group sees the solution of all those topics as a subject for an ENTSO-E forum because experts in restoration issues and owners and operators of SPGMs, synchronous condensers or SVCs are not involved in this expert group.
- / Future chapter 5 of this paper will give an overview of expected problems in the final report.

# ADDITIONS PLANNED FOR THE FINAL REPORT

- / Chapter 4: Gap Analysis of Connection Codes
- / Chapter 5: Which technologies can provide these services?
- / Chapter 6: Compliance Verification and Performance Monitoring
- / Chapter 7: Roadmap for delivering capabilities
- / Chapter 8: Recommendations for future work
- / Chapter 9: Summary